CMPT231 Lecture 4: ch8, 11 Linear-time Sort and Hash Tables

Psalm 90:10-12 (ESV)

The **years of our life** are seventy, or even by reason of strength eighty;

yet their span is but **toil** and **trouble**; they are soon gone, and we **fly away**.

Who considers the power of your anger, and your wrath according to the fear of you?

So teach us to **number our days** that we may get a **heart of wisdom**.

 Proving all comparison sorts are l (n lg n) Linear-time non-comparison sorts: Counting sort Radix sort and analysis Bucket sort and probabilistic proof • Hash tables: Collision handling by chaining Hash functions and universal hashing Collision handling by open addressing

Summary of sorting algorithms

• Comparison sorts (ch2, 6, 7):

- Insertion sort: V (n^2), easy to program, slow
- Merge sort: V (n lg n), out-of-place copy (slow)
- Heap sort: V (n lg n), in-place, max-heap
- Quicksort: V (n^2) worst-case, V (n lg n) average

and small (fast) constant factors

- Linear-time non-comparison sorts (ch8):
 - Counting sort: k distinct values: V (k)
 - Radix sort: d digits, k values: V (d(n+k))
 - Bucket sort: uniform distribution: V (n)

Comparison sorts are $\Omega(n \lg n)$

- **Decision tree** model of computation:
 - Leaves are possible outputs
 - i.e., permutations of the input
 - Nodes are decision points
 - i.e., when **comparisons** are made
 - A path through the tree is one run of algorithm
- Num leaves = num permutations = n!
- Num comparisons = num nodes along path
- So worst-case complexity = depth of tree:
 - = l (lg(num leaves)) = l (lg(n!))
 - $= l (n \lg n) (by Stirling).$

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Linear-time sorts

- Ways to beat the V (n lg n) barrier
- By using **assumptions** on input:
 - e.g., known range or distribution of values
 - e.g., numeric values we can perform arithmetic on
- But linear-time sorts not always worth it
- For real-world arrays, V (n) and V (n lg n) are very similar

• Up to $n = 10^6$, $\lg n < 21$, a smallish factor

 For realistic n, a fast n lg n sort like Quicksort may have smaller constants than a linear-time sort
 cmpt231.seanho.com/leButPlecursion is expensive (function calls)

Hybrid algorithms

- (#7.4-5) : QuickSort + Insertion sort
 - One pass with Quicksort, stop when length < c</p>
 - Second pass with insertion sort
 - Items shift at most c positions over
- TimSort: Merge sort + Insertion sort
 - Default in Python, Java (<7), Android, etc
 - Take advantage of monotone runs in real data
 - Use run stack to track merges and exploit cache locality
 - Merge with minimal extra memory or copying
 - Stable, best-case O(n), worst O(n lg n)

Counting sort

- Assume: values are integers in {0, ..., k}
- Out-of-place sort:
 - Census array (size k) tallies a histogram
 - Items copied into output array
- Stable: preserves order of duplicates
- Complexity: V (n+k) (watch out if k gets too big!)

Radix sort

- (How IBM made its fortune! Punch cards, ca 1900)
- Assume: values have at most d digits
- Sort one digit at a time, least-significant first
 MSD using recursion (with call overhead)
- Use a stable sort, e.g., counting sort (why?)

<pre>def radix_sort(A, n, d): for i in 1 d:</pre>	3	7	4	5
stable_sort(A on digit i)	2	9	1	3
	1	0	1	6
	2	0	1	6
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Radix sort: complexity

- Input: n items of d digits, each with k values (e.g., k=10)
- e.g., using counting sort as the stable sort:
 - d iterations, each V (n+k)
 - So total complexity is V (d(n+k))
- Digits need not be base k=10 !
 - Smaller base k ⇒ more iterations d
 - Fewer digits d ⇒ each counting sort V (n+k) takes longer

Radix: choosing digit size

- b-bit items can be split into r-bit digits:
 - Then $d = \frac{b}{r}$ digits, each with $k = 2^r 1$ values
 - e.g., b = 32-bit items in r = 8-bit digits ⇒ d = 4, k
 = 255
- Choose $r = \lg n$: then $\Theta\left(\left(\frac{b}{r}\right)(n+2^r)\right)$ = $\Theta\left(\left(\frac{b}{\lg n}\right)(2n)\right) = \Theta\left(\frac{bn}{\lg n}\right)$
- e.g., to sort n = 2¹⁶ integers of b = 64-bits:
 ⇒ Use r = 16-bit digits

- Proving all comparison sorts are l (n lg n)
- Linear-time non-comparison sorts:
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 - Radix sort and analysis
 - Bucket sort and probabilistic proof
- Hash tables:

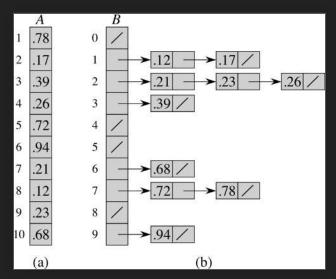
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Bucket sort

Assume: values uniformly distributed over [0,1)

(For range [a, b), use linear transform to [0, 1))

- Divide *[0,1)* into *n* equal **buckets**
 - Can use **array**, or
 linked list, etc.
- **Distribute** input into buckets:
 V (n)
- **Sort** each bucket (e.g., **insertion** sort)



Bucket sort: complexity

- Let n_i be number of items in the i-th bucket
 Sorting a bucket with insertion sort takes O(n_i²)
- Intuition: uniform distribution \Rightarrow $n_i \approx 1$
- **Expected** time of bucket sort: E[T(n)]

$$= E \Big[\Theta(n) + \sum O(n_i^2) \Big]$$

= $\Theta(n) + O \Big(\sum E[n_i^2] \Big)$ (linearity of expectation)
= $\Theta(n) + O \Big(\sum \Big(2 - \frac{1}{n} \Big) \Big)$ (by lemma)
= $\Theta(n) + O(2n - 1) = O(n)$

Lemma: $E[n_i^2] = 2 - 1/n$

- Use indicator var: X_{ij} = 1 iff j-th item falls in i-th bucket
- Number of items in i-th bucket is $n_i = \sum_{j=0}^{n} X_{ij}$

• So
$$E[n_i^2] = E\left[\left(\sum_{j=0}^{n-1} X_{ij}\right)^2\right]$$

 $= \sum_{j=0}^{n-1} E[X_{ij}^2] + 2\sum_{j=0}^{n-1} \sum_{k=0}^{j-1} E[X_{ij}X_{ik}]$

Think of these as entries in a j-k matrix
 Consider diagonal and off-diagonal terms
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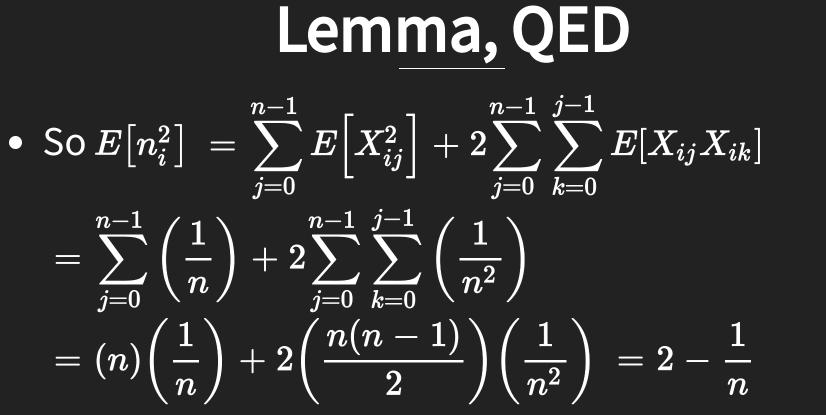
Lemma, continued

$$ullet \; \; Eig[n_i^2ig] = \sum_{j=0}^{n-1} Eig[X_{ij}^2ig] + 2 \sum_{j=0}^{n-1} \sum_{k=0}^{j-1} E[X_{ij}X_{ik}]$$

• For diagonal terms:

$$E\Big[X_{ij}^2\Big] = 0^2 P(X_{ij}=0) + 1^2 P(X_{ij}=1) \ = 1^2 \left(rac{1}{n}
ight) = rac{1}{n}$$

• For off-diagonal terms: items $j \neq k$ are independent, so $E[X_{ij}X_{ik}] = E[X_{ij}]E[X_{ik}] = \left(\frac{1}{n}\right)\left(\frac{1}{n}\right) = \frac{1}{n^2}$



- This proves the lemma, proving bucket sort is V (n)
- Assumptions: input values uniformly distributed

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Hash tables

- **Dictionary** of key-value pairs, with this **interface**:
 - insert(T, k, x):add item x with key k
 - search(T, k): find an item with key k
 - delete(T, x): remove specific item x
- Better than regular array (direct addressing) when:
 - Range of possible keys too huge to allocate
 - Actual keys are only sparse subset of possible keys
- e.g., only have items at keys 0, 2, 40201300:
 Direct addressing would allocate 40,201,300 entries!

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Hashing

- Hash function h(k): U → Z_m (i.e., {0, ..., m-1}) maps from universe U of possible keys to a set of m buckets
 Use h(k) as key instead of k
- Hash collision: two keys, same bucket: $h(k_i) = h(k_j)$
 - A good hash function should minimise collisions
 - Various collision handling methods
 - Let's start with chaining via linked lists
- Similar to **bucket sort**, but
 - Hash function maps unknown distribution of keys in U to uniform distribution on buckets

Hash table operations

- Assuming collision handling via linked lists:
- insert(T, k, x):
 - insert x at head of list at bucket h(k)
 - O(1) complexity; assumes x not already in list
- search(T, k):
 - linear search every item in bucket h(k)
 - $O(n_{h(k)})$, where $n_{h(k)}$ = num items in bucket h(k)
- delete(T, x):

 $O(n_{h(k)})$

- if arg is a pointer directly to item, then O(1)
- if arg is a key, then need to search for it first:

Load factor

Search efficiency depends on how full buckets are:

 $n_{h(k)}$

- Load factor v = n/m:
 - n = total number of items stored in hash table
 - m = number of buckets
 - v is average num items per bucket: $E[n_{h(k)}]$
- Unsuccessful search takes average V(1+v)
 - Computing the hash function takes V (1)
 - Linear search goes through entire bucket
 - Expected length of bucket's linked list is v
- Successful search is also V (1+v):

Hash table search: $\Theta(1+\alpha)$

- Num items searched = position of x in linked list at h(k)
 - = Number of collisions after x was inserted
- Use an indicator: $X_{ij} = 1$ iff $h(k_i) = h(k_j)$
 - P(i and j collide) = $E[X_{ij}] = 1/m$
- Expected num items searched:

$$= E\left[\left(\frac{1}{n}\right)\sum_{i} (\text{num items})\right]$$
$$= E\left[\left(\frac{1}{n}\right)\sum_{i} \left(1 + \sum_{i} X_{ij}\right)\right] (\text{number of collisions})$$

Successful search is $\Theta(1+\alpha)$

$$= \left(\frac{1}{n}\right) \sum_{i} \left(1 + \sum_{j} E[X_{ij}]\right) \text{ (linearity of expectation)}$$
$$= \left(\frac{1}{n}\right) \sum_{i} \left(1 + \sum_{j} \left(\frac{1}{m}\right)\right) \text{ (probability of collision)}$$
$$= \left(\frac{1}{n}\right) \sum_{i} 1 + \left(\frac{1}{nm}\right) \sum_{i} \sum_{j} 1 \text{ (independent of i, j)}$$
$$= 1 + \left(\frac{1}{nm}\right) \left(\frac{n(n-1)}{2}\right) = 1 + \frac{\alpha}{2} - \frac{\alpha}{2n}$$

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Hash functions

- Assume $U = \mathbb{N} = \{1, 2, 3, ...\}$
 - i.e., keys can be converted to natural numbers
 - e.g., strings encoded using ASCII or UTF-8
- Want h(k) uniformly distributed on \mathbb{Z}_m
 - But distribution of keys k is unknown
 - Also, keys k_i and k_j might not be independent
- Various hashing strategies:
 - Division hash
 - Multiplication hash
 - Universal hashing

Division hash

- h(k) = k mod m
 - Simplest function mapping $\mathbb{N} \to \mathbb{Z}_m$
- Fast to compute: if $m = 2^p$ (i.e., a power of 2), this is just selecting the p least-significant bits
- But: if k is a string using a radix-2^p representation, then permuting the string gives same hash (#11.3-3)
- So try m prime and not too close to a power of 2

Multiplication hash

h(k) = floor(m(kA mod 1)) (choose constant 0 < A < 1)

- Multiply $k \ast A \rightarrow take fractional part$
- \rightarrow multiply by m \rightarrow round down
- Fast implementation using $m = 2^p$:
 - Let w be the native machine word size (num bits)
 - Choose a w-bit integer s ($0 < s < 2^w$) and let A = $\frac{s}{2^w}$
 - Multiply s*k: product has 2w bits in two words
 - r_0, r_1

Select the p most-significant bits of lower word

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Universal hashing

- For any fixed choice of hash function, can always find bad input resulting in lots of hash collisions
- Why not **randomly** select from a **pool** H of hash functions?
- Want pool to have **universal hash** property:
 - For any two keys j ≠ k, at most |H|/m hash functions in H cause a collision: h(j) = h(k)
 i.e., P(h(j) = h(k)) ≤ 1/m
- Then expected bucket size is still O(1+v)
 So average complexity of search is still O(1)

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Open addressing

- Another method of collision handling:
 - Store keys directly in table, no linked lists
- Hash function $h: U \times \mathbb{Z}_m \to \mathbb{Z}_m$
 - A probe sequence is h(k,0), h(k,1), h(k,2), ...
- To insert an item in table, first try h(k,0)
 - If already occupied, try next in sequence: h(k,1)
 - Will eventually try all slots (full coverage)
 - if probe sequence is a permutation of \mathbb{Z}_m
- Search is similar: check if found desired key
- Hash table will still overflow if n > m

Probe <u>sequencing</u>

- Choose a hash function that gives us uniform hashing:
 - Each of the m! permutations of Z_m is equally likely to be the probe sequence for a given key
- Linear probing: h(k,i) = h(k) + i
 - Try h(k), then h(k)+1, etc. (modulo m)
 - But: long runs get longer (more likely to hit)
- Quadratic probing: $h(k,i) = h(k) + c_1 i + c_2 i^2$
 - Must choose c_1, c_2 to ensure full coverage
 - But: collision on initial h(k) ⇒ full sequence collision

Double hashing

- Use two hash functions: $h(k, i) = h_1(k) + ih_2(k)$
 - Try $h_1(k)$ first, then use h_2 to jump around
- For full coverage, ensure m and h₂(k) are relatively prime
 - i.e., no common factors other than 1
 - e.g., let $m = 2^p$ and ensure $h_2(k)$ always odd
 - e.g., let m be prime, and ensure $1 \le h_2(k) \le m$
- Each combination of h₁(k) and h₂(k) yields a different probe sequence:
 - Total number of sequences is $\Theta(n^2)$

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Visualisations of sorting

- The Sound of Sorting (YouTube playlist)
- Visualgo: interactive demos:
 - sorting, binary heaps, hash tables, etc.
- Toptal: Comparison of sort algorithms
- Mike Bostock's "Visualizing Algorithms":
 Fisher Vatos shuffle, sorting

Fisher-Yates shuffle, sorting

